

GENERALIZED PATH DEPENDENT
REPRESENTATIONS FOR GAUGE THEORIES

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PLAN OF THE TALK

- **INTRODUCTION: THE CONCEPT OF PATH DEPENDENCE**
- **DEFINITION OF THE PATH OPERATOR**
- **GEOMETRICAL INTERPRETATION: THE GENERATOR OF CURVES**
- **APPLICATION: DERIVATION OF COVARIANT TAYLOR SERIES**
- **CONCLUSIONS**

THE NOTION OF PATH DEPENDENCE

- Dirac's work on the nonintegrability of the phase of wave functionals in quantum mechanics P. A. M. Dirac, *Proc. Roy. Soc. Lond. A* 133, 60 (1931).

- Mandelstam first introduce an end point derivative in gauge theory S. Mandelstam, *Annals Phys.* 19, 1 (1962), *Annals Phys.* 19, 25 (1962).

- Integral formulation of Wu and Yang C. N. Yang, *Phys. Rev. Lett.* 33, 445 (1974); T. T. Wu and C. N. Yang, *Phys. Rev. D* 12, 3845 (1975).

- The loop representation in loop quantum gravity R. Gambini and A. Trias, *Phys. Rev. D* 22, 1380 (1980), *Phys. Rev. D* 23, 553 (1981); X. Fuster, R. Gambini and A. Trias, *Phys. Rev. D* 31 (1985) 3144.

MOTIVATION: TOWARD A UNIFIED VIEWPOINT

We concentrate in **gauge theories** where several and different definitions of path dependent operators have been made. They depend essentially on

- The space where path dependent functionals take values is either the space of **open or closed curves**.
- The nature of the **variation is due to a point or many points**, which have been usually called end point derivatives and area derivatives respectively.
- **The place where the variation is appended**, is on the curve or in other place on the manifold.

DEFINITION OF THE PATH OPERATOR

- We define the path derivative of the functional $\Psi(\alpha)$ for a given path α by

$$\mathcal{D}\Psi(\alpha) = \Delta\Psi(\alpha) - \Psi(\alpha) \quad (1)$$

where the action of $\Delta : \Psi(\alpha) \rightarrow \Psi'(\alpha')$, is to displace infinitesimally and continuously the initial curve α to a deformed curve α' with some transforming action on Ψ .

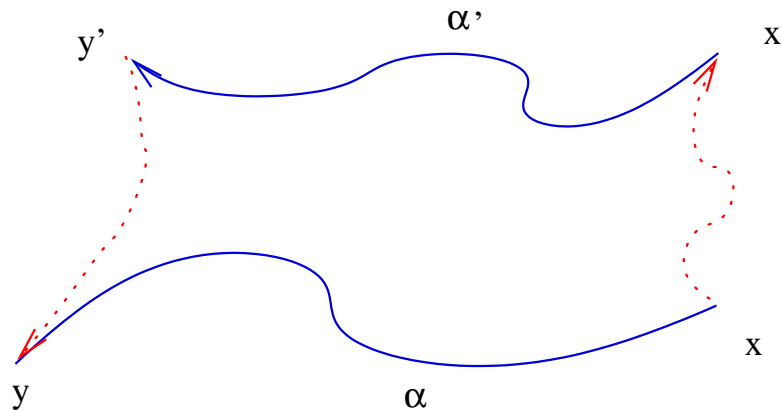


Figure 1: Deformation of the curve $\alpha \rightarrow \alpha'$.

- We assume a transformation of a matrix functional $\Psi_{AB}(\alpha)$ under the action of the deformation by

$$\Delta\Psi_{AB}(\alpha) = U_A^{A'}(\delta y^{-1}) \Psi_{A'B'}(\alpha') U_B^{B'}(\delta x) \quad (2)$$

where the elements $U_B^{B'}(\delta x)$ and $U_A^{A'}(\delta y^{-1})$ are functions of the paths δx and δy^{-1} .

- We take U elements to be parallel propagators
- For the curve deformation that just moves one point along a straight line, we define the **point deformations**

$$\mathcal{D}_{\delta y} \Psi_{y,x} = \delta \Psi_{y,x} + \delta y^\mu A_\mu(y) \Psi_{y,x}, \quad (3)$$

$$\mathcal{D}_{\delta x} \Psi_{y,x} = \delta \Psi_{y,x} - \Psi_{y,x} \delta x^\mu A_\mu(x) \quad (4)$$

And for the curve deformation with x and y fixed but that encloses some area, the **loop deformation**

$$\mathcal{D}_L \Psi_{y,x} = \delta \Psi_{y,x} \quad (5)$$

ACTION OF THE GROUP OF LOOPS

The construction can be understood in terms of the action of the group of loops L on arbitrary paths γ . Let us consider the same path α as before and focus on the loop $l = \delta x \circ \alpha' \circ \delta y^{-1} \circ \alpha^{-1}$ with composition $l \circ \alpha = \delta x \circ \alpha' \circ \delta y^{-1}$. The variation of a functional $\Delta\Psi(\alpha)$ will be represented by an operator $U(l)$ with $l \in L$ as,

$$\Delta\Psi(\alpha) = \Psi(l \circ \alpha) = U(l)\Psi(\alpha), \quad (6)$$

and therefore we have

$$\Psi(\alpha') = U(\delta y) \left[U(l) \Psi(\alpha) \right] U(\delta x^{-1}). \quad (7)$$

COVARIANT DIFFERENTIATION OF GAUGE OBJECTS

Here we compute the action of the path derivative on phase factors. Let us consider the ordered phase factor of the same path α as before,

$$U_{y,x}(\alpha) = \mathcal{P}_\sigma \left(\exp \int_0^1 -A_\mu(\sigma) \frac{d\alpha^\mu(\sigma)}{d\sigma} d\sigma \right), \quad (8)$$

We partition the paths α and α' in N segments.

$$U(\alpha') = \prod_{i=0}^N U(\alpha'_{i+1,i}) = U'_{N+1,N} \cdots U'_{2,1} U'_{1,0}, \quad (9)$$

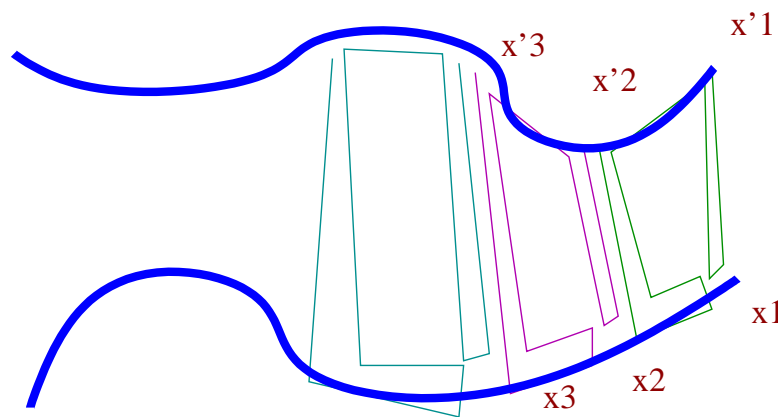


Figure 2: Intermediate paths

We have

$$\mathcal{D}U(\boldsymbol{\alpha}) = \prod_{i=0}^N \left(U(\boldsymbol{\alpha}_{i+1,i}) H(\boldsymbol{x}_i) \right) - U(\boldsymbol{\alpha}), \quad (10)$$

Using the non abelian Stokes theorem to lowest order

$$H(\boldsymbol{x}_i) = 1 - \int_0^1 \mathcal{F}_{\mu\nu}(\boldsymbol{x}_i) N^\mu(\boldsymbol{\sigma}_i, t) \frac{\partial x_i^\nu}{\partial \sigma} d\sigma_i dt, \quad (11)$$

where $\mathcal{F}_{\mu\nu}(\boldsymbol{x}_i) = U(\delta x_i) F_{\mu\nu}(\boldsymbol{x}_i) U(\delta x_i^{-1})$ is the parallel transported curvature. Replacing, we have

$$\mathcal{D}(N) U(\boldsymbol{\alpha}) = - \int_0^1 \sum_{i=0}^N U_{i+1,i} \mathcal{F}_{\mu\nu}(\boldsymbol{x}_i) N^\mu(\boldsymbol{\sigma}_i, t) \frac{\partial x_i^\nu}{\partial \sigma} d\sigma_i dt \quad (12)$$

The continuum limit of the above equation gives

$$\mathcal{D}(N) U(\boldsymbol{\alpha}) = - \int_0^1 dt \int_0^1 d\sigma U_{y,x(\boldsymbol{\sigma},t)} \mathcal{F}_{\mu\nu}(\boldsymbol{x}(\boldsymbol{\sigma},t)) U_{x(\boldsymbol{\sigma},t),x} N^\mu(\boldsymbol{\sigma},t) \frac{\partial x^\nu(\boldsymbol{\sigma},t)}{\partial \sigma}$$

THE GENERATOR OF CURVES

We introduce a family of deformed curves $\alpha_t(\sigma)$

$$\Psi(\alpha_{n+1}) = \Psi(\alpha_n) + \Psi(\alpha_n)A_{x_n} - A_{y_n}\Psi(\alpha_n) + \mathcal{D}(N_n)\Psi(\alpha_n), \quad (13)$$

Iterating the above equation

$$\Psi(\alpha') = U(\alpha(1)) \left[\mathcal{P}_t \left(\exp \int_0^1 dt \mathcal{D}_t \right) \Psi(\alpha) \right] U(\alpha^{-1}(0)), \quad (14)$$

therefore we identify $U(l) = \mathcal{P}_t \left(\exp \int_0^1 dt \mathcal{D}_t \right)$

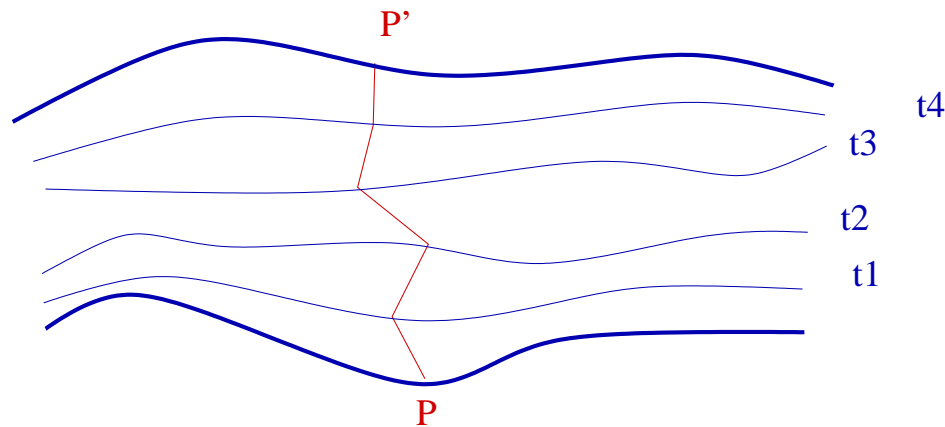


Figure 3: Flow of the point P under the diffeomorphism

COVARIANT TAYLOR SERIES

- Covariant Taylor expansions were developed as part of a method of calculation to find the effective action in quantum field theories.

A. O. Barvinsky and G. A. Vilkovisky, *Phys. Rept.* 119, 1 (1985); S. M. Kuzenko and I. N. McArthur, *JHEP* 0305, 015 (2003).

STANDARD DERIVATION

• Using the transport equation $\frac{D\dot{x}^\nu}{dt} = \dot{x}^\mu D_\mu \dot{x}^\nu(t) = 0$ one can show that for the scalar function $f(\mathbf{x}(t))$ one has for all n ,

$$\frac{d^n f(\mathbf{x}(t))}{dt^n} = [D_{\nu_n} \dots D_{\nu_1} f(\mathbf{x})]_{\mathbf{x}=\mathbf{x}(t)} \dot{x}^{\nu_1} \dots \dot{x}^{\nu_n}. \quad (15)$$

Then, considering the expansion and defining,

$$\sigma^\mu(\mathbf{x}_1, \mathbf{x}_2) = (t_2 - t_1) \left[\frac{dx^\mu(t)}{dt} \right]_{t=t_1}, \quad (16)$$

we arrive to the expression,

$$f(\mathbf{x}_2) = \sum_{n=0}^{\infty} \frac{1}{n!} \sigma^{\nu_1}(\mathbf{x}_1, \mathbf{x}_2) \dots \sigma^{\nu_n}(\mathbf{x}_1, \mathbf{x}_2) D_{\nu_n} \dots D_{\nu_1} f(\mathbf{x}_1). \quad (17)$$

We consider the field composed with the two parallel propagators as $U(x', x) \varphi(x) U(x, x')$. Since the composition behaves as a scalar with respect to the point x

$$U(x'', x') \varphi(x') U(x', x'') = \sum_{n=0}^{\infty} \frac{1}{n!} \sigma^{\nu_1}(x, x') \dots \sigma^{\nu_n}(x, x') D_{\nu_n}^x \dots D_{\nu_1}^x \times U(x'', x) \varphi(x) U(x, x'). \quad (18)$$

Using the identity

$$\sigma^{\nu_1}(x, x') \dots \sigma^{\nu_n}(x, x') D_{\nu_n}^x \dots D_{\nu_1}^x U(x', x) = 0, \quad (19)$$

We obtain the covariant Taylor series for the field $\varphi(x)$, taking $x'' = x'$ and multiplying by $U^{-1}(x, x')$ and $U^{-1}(x', x)$,

$$U(x, x') \varphi(x') U(x', x) = \sum_{n=0}^{\infty} \frac{1}{n!} \sigma^{\nu_1}(x, x') \dots \sigma^{\nu_n}(x, x') D_{\nu_n} \dots D_{\nu_1} \varphi(x). \quad (20)$$

GEOMETRICAL DERIVATION

Let us define the path dependent field $\Psi(\gamma) = U(\gamma_2) \phi(x) U(\gamma_1)$

- The first deformation is $\Psi(\gamma') = U(D)\Psi(\gamma)$
- The second deformation is $\Psi(\gamma'') = U(\gamma_2^{-1}) [U(D')\Psi(\gamma')] U(\gamma_1^{-1})$

Both deformations can be viewed as one point deformation $D_{\delta x}$

$$\Psi(\gamma'') = U(\gamma_2^{-1}) [U(D_{\delta x})\Psi(\gamma)] U(\gamma_1^{-1}). \quad (21)$$

We obtain covariant Taylor expansions with $\delta x = x' - x$

$$U(x, x') \phi(x') U(x', x) = \sum_{n=0}^{\infty} \frac{1}{n!} \delta x^{\nu_1} \dots \delta x^{\nu_n} D_{\nu_n} \dots D_{\nu_1} \phi(x), \quad (22)$$

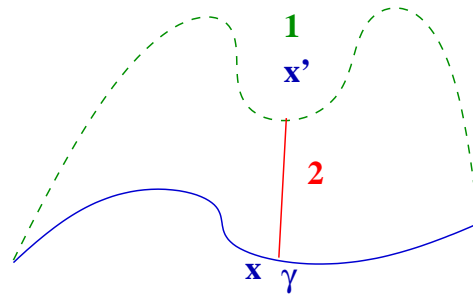


Figure 4: Two deformations of the curve γ .

DISCUSION Y CONCLUSION

- We have defined a path dependent operator in gauge theory, which is covariant by construction, and acts by **continuous deformations** on the space of smooth curves $\Gamma(M)$
- We have established a relation between the path derivative introduced here and the **area** and **end point** derivative.
- We have calculated the **finite variation** of a functional when its argument is changed by successive infinitesimal deformations.
- We have derived **covariant Taylor expansions** for non Abelian fields by considering the deformation of open curves.