

The program of Loop Quantum Gravity

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But, how can we integrate over a space of connections? It is mandatory to endow this space with a measure.

Making a measure

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The key idea is to assign a group element $g_e \in G$ to each edge e of a graph embedded into the spatial manifold Σ .

If we achieve to identify \mathcal{A} with something like G^∞ then we can take the fact that the infinite product of *probability* measure spaces is well defined and because G is a compact group we could obtain \mathcal{DA} through the products of the Haar measure on G , in other words:

$$\mathcal{DA} = \prod_e dg_e$$

To make it, define the space \mathcal{A}_e by

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Then, fixing a trivialization of the bundle in the endpoints of the curve e we may identify \mathcal{A}_e with a copy of the group G and hence,

$$\mathcal{A} = \mathcal{A}_{e_1} \times \cdots \times \mathcal{A}_{e_n} \cong G^n.$$

With all that we define a space $Fun_0(\mathcal{A})$ as the space generated by functionals $\psi(A)$ of the form

$$\psi(A) = f \left(\text{P exp} \int_{e_1} A, \dots, \text{P exp} \int_{e_n} A \right).$$

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And $Fun(\mathcal{A})$ as the completion of $Fun_0(\mathcal{A})$ in the sup norm

$$\|\psi\|_\infty = \sup_{A \in \mathcal{A}} |\psi(A)|.$$

Because of the identification $\mathcal{A} \longleftrightarrow G^n$ we can now define a measure on $Fun(\mathcal{A})$:

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Now is time to define the kinematical Hilbert space $\mathcal{H}_{Kin} = L^2(\mathcal{A})$ for our theory as the completion of $Fun(\mathcal{A})$ with respect to the norm

$$\|\psi\|_2 = \left[\int_{\mathcal{A}} |\psi|^2 d\mu \right]^{1/2} .$$

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The invariant states under gauge transformations are wave functions $\Psi[A]$ on the quotient of \mathcal{A} by the group \mathcal{G} of gauge transformations, namely, $L^2(\mathcal{A}/\mathcal{G})$.

Spin network states

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Consider an graph Γ embedded in the manifold Σ . Choose an orientation for each link e in the graph and assign it an irreducible representation ρ_e of G . Then, $H_e[A] = \rho_e \left(\text{P exp} \int_e A \right)$ can be seen as a matrix with components $H_e[A]_j^i$. Now, take the tensor product of all these matrices and obtain a “big tensor” $H(A)$.

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We get a *spin network state* by the contraction of all the indices of $H(A) \otimes I$.

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- By the later, *spin network states* are solutions to Gauß constraint!.

Quantization of diffeomorphism constraint

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What do we mean when we talk about diffeomorphism invariant states?

Representation of $Diff(\Sigma)$ on \mathcal{H}_{kin}^*

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Consider an operator U_ϕ , $\phi \in Diff(\Sigma)$, associated with the diffeomorphism transformations and such that:

$$(U_\phi \Phi) \Psi_S = \Phi (U_\phi \Psi_S) = \Phi (\Psi_{\phi(S)}),$$

where $\Phi \in \mathcal{H}_{kin}^*$ and $\Psi_{\phi(S)}$ is the spin network state which results by applying ϕ to each one of his labels $S = (\Gamma, j_e, i_n)$ in a specific manner.

The diffeomorphism invariant states are those which satisfies

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And the solutions of this equation are given by states of the form

$$|\Psi_S\rangle = \sum_{\Psi_{S'} \in \mathcal{O}(\Psi_S)} |\Psi_{S'}\rangle$$

where $\mathcal{O}(\Psi_{S'})$ denotes the orbit of $\Psi_{S'}$ under the $Diff(\Sigma)$ -action. These states don't change when \mathcal{U}_ϕ acts on them.

Now, to conclude the quantization of diffeomorphism constraint, we define the scalar product between two of such states as

$$(\Psi_S | \Psi_{S'}) = \sum_{\Psi_{S''} \in \mathcal{O}(\Psi_S)} \langle \Psi_{S''} | \Psi_{S'} \rangle .$$

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Hence, the states in \mathcal{H}_{kin}^* which don't change with the action of \mathcal{U}_ϕ are the states which solve the diffeomorphism constraint!.

Quantization of scalar constraint

The general idea is to put the constraint in the form

$$\mathcal{S}[N] = \int_{\Sigma} d^3x N \epsilon^{abc} \delta_{ij} F_{ab}^i \{A_c^j, \mathbf{V}\}$$

where \mathbf{V} is the volume of Σ .

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Taking into account that for an infinitesimal loop α on a plane, the curvature and the Poisson bracket above are regularized as follow

$$\begin{aligned} H_{\alpha}[A] - H_{\alpha}^{-1}[A] &= \epsilon^2 F_{ab}^i \tau_i + O(\epsilon^4) \\ H_{e_a}^{-1} \{H_{e_a}[A], V\} &= \epsilon \{A_a^i, V\} + O(\epsilon^2), \end{aligned}$$

the operator becomes:

$$\hat{\mathcal{S}}[N] = \lim_{\epsilon \rightarrow 0} \sum_I N_I \epsilon^{abc} \text{tr} \left[\left(\hat{H}_{\alpha}[A] - \hat{H}_{\alpha}^{-1}[A] \right) \hat{H}_{e_a}^{-1} \left\{ \hat{H}_{e_a}[A], \hat{V} \right\} \right]$$

This limit doesn't exist in general, but does in the Hilbert space of diffeomorphism invariant states because there, the dependence of ϵ becomes trivial. The analysis of scalar constraint involves a lot of subtleties and technical procedures that I am not going to show here (see the references).

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