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The cosmological constant in 3d gravity:
towards a unified approach

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ref: C. Meusburger, Geometrical (2+1)-gravity and the Chern-Simons formulation: grafting, Dehn twists, Wilson loop observables and the cosmological constant gr-qc/0607121, to appear in Commun. Math. Phys.
C. Meusburger, B.J. Schroers, in preparation

- Contents:
1. background: 3d gravity and the cosmological constant
 2. Lie algebras and Lie groups in 3d gravity
a unified description
 3. application: Wilson loops
 4. Poisson-Lie structures in 3d gravity
and the phase space
 5. Outlook and Conclusions

①

3d gravity

- Euclidean signature
- Lorentzian signature
- $\lambda > 0, \lambda = 0, \lambda < 0$

$$\gamma_E = \text{diag}(1, 1, 1)$$

$$\gamma_L = \text{diag}(1, -1, -1)$$

geometrical viewpoint

- Einstein-Hilbert action

$$S_{EH} = \int_M e^a \lambda (dw_a + \frac{1}{2} \epsilon_{abc} w^b \wedge w^c) + \frac{\Lambda}{6} \epsilon_{abc} e^a \wedge e^b \wedge e^c$$

- solution of Einstein equations as quotients of model spacetimes $\mathbb{X}_{\lambda, S}$

Euclidean $\lambda < 0$

$\mathbb{X}_{\lambda, S}$

$\lambda = 0$

H^3

$\lambda > 0$

S^3

$J_{SO(4)}(\mathbb{X}_{\lambda, S})$

$SL(2, \mathbb{C})$

$SU(2) \times \mathbb{R}^3$

$SU(2) \times SU(2)$

Lorentzian $\lambda < 0$

dS^3

$\lambda = 0$

M^3

$\lambda > 0$

AdS^3

$SL(2, \mathbb{C})$

$SL(2, \mathbb{R}) \times \mathbb{R}^3$

$SL(2, \mathbb{R}) \times SL(2, \mathbb{R})$

Chern-Simons viewpoint

- Chern-Simons action $S_{CS} = \int_M \langle A \wedge dA + \frac{2}{3} A \wedge A \wedge A \rangle$ $A = e^a P_a + \omega^a J_a$
- gauge group $H_\lambda = J_{SO(4)}(\mathbb{X}_\lambda)$
- Lie algebra $\mathfrak{h}_\lambda = \text{Lie } H_\lambda$: generators $J_0, P_a, a=0, 1, 2$
 - Lie bracket $[J_a, J_b] = \epsilon_{abc} J^c$ $[J_a, P_b] = \epsilon_{abc} P^c$ $[P_a, P_b] = \lambda \epsilon_{abc} J^c$
 - Ad-invariant symmetric ILFs $\langle J_a, J_b \rangle = 0$ $\langle J_a, P_b \rangle = \gamma_{ab}$ $\langle P_a, P_b \rangle = 0$
 - $S(J_a, J_b) = \gamma_{ab}$ $S(J_a, P_b) = 0$ $S(P_a, P_b) = \lambda \gamma_{ab}$

phase space

on manifolds $\mathbb{R} \times S$: Hamiltonian formulation

phase space = { flat H_λ -connections on S } / gauge transformations

- finite dimensional

- parametrised by holonomies along generators of $\Pi_1(S)$

- physical observables: Wilson loops

Poisson structure:

- given by classical r-matrix for H_λ

- particles $\hat{=}$ dual Poisson-Lie structure

- handles $\hat{=}$ Heisenberg double Poisson structure

\Rightarrow depending on signature and sign of λ :

1. different Lie groups H_λ (gauge / isometry groups)

2. different Poisson-Lie structures (phase space)

3. different quantum groups (quantum symmetries)

\Rightarrow • unified description for $\lambda > 0, \lambda = 0, \lambda < 0$

in which structural similarities apparent?

• λ as a deformation parameter?

- \rightarrow relate Lie groups H_λ

- \rightarrow relate Poisson-Lie structures

- \rightarrow relate quantum groups

② Lie groups in 3d gravity
- a unified description

(2A) unified description of the Lie algebras in 3d gravity

commutative ring $R_\lambda = (\mathbb{R}^2, +, \cdot)$

- elements $a+\theta b$, $a, b \in \mathbb{R}$
- addition $(a+\theta b) + (c+\theta d) = (a+c) + \theta(b+d)$
- multiplication

$$(a+\theta b) \cdot (c+\theta d) = (ac + \lambda bd) + \theta(ad + bc)$$

- generalises construction of \mathbb{C}
- formal parameter θ , $\theta^2 = \lambda$

unified description of the gravity Lie algebras \mathfrak{h}_λ

- 3d Lorentz/rotation algebra

$$[J_a, J_b] = \epsilon_{abc} J^c \quad \kappa(J_a, J_b) = \gamma_{ab}$$

- extend Lie bracket and Killing form bilinearly to R_λ

- with identification $P_a = \theta J_a$

→ recover Lie bracket of \mathfrak{h}_λ

→ recover the Ad-invariant symmetric BLFs on \mathfrak{h}_λ

$$\kappa = S + \theta \cdot \langle , \rangle$$

⇒ gravity Lie algebras \mathfrak{h}_λ :

$\mathfrak{h}_\lambda = \text{su}(2, R_\lambda)$ for Euclidean signature

$\mathfrak{h}_\lambda = \text{sl}(2, R_\lambda)$ for Lorentzian signature

2B

The unified description of the gravity Lie groups H_Λ

→ idea: use identification of $SL(2, \mathbb{R}), SU(2)$ with (pseudo) quaternions

(pseudo) quaternions H

associative algebra over \mathbb{R} with generators $e_a, a=0,1,2$ and relations

$$e_a \cdot e_b = 2_{ab} + \epsilon_{abc} e^c \quad \left. \begin{array}{l} \text{Clifford algebra relations} \\ + \text{Lie bracket} \end{array} \right\}$$

$$H = \{ q_3 \cdot 1 + q^a e_a \mid q_3, q^a \in \mathbb{R} \}$$

group of unit (pseudo) quaternions

$$H_1 = \{ q_3 \cdot 1 + q^a e_a \mid q_3, q^a \in \mathbb{R}, q_3^2 + 2_{ab} q^a q^b = 1 \}$$

Euclidean: $H_1^E \cong SU(2)$ Lorentzian: $H_1^L \cong SL(2, \mathbb{R})$

unified description of the gravity Lie groups H_Λ

quaternions over ring R_Λ

$$H(R_\Lambda) = \{ q_3 \cdot 1 + q^a e_a \mid q_3, q^a \in R_\Lambda \}$$

⇒ **Theorem**

The unit quaternions over the ring R_Λ form a group isomorphic to the gravity Lie groups H_Λ

$$H_\Lambda \cong H_1(R_\Lambda) = \{ q_3 \cdot 1 + q^a e_a \mid q_3, q^a \in R_\Lambda, q_3^2 + 2_{ab} q^a q^b = 1 \}$$

③

Application: Wilson loop observables

Wilson loop observables: Conjugation invariant functions of holonomies along closed curves

identification $H_\lambda \cong H_1(R_\lambda)$:

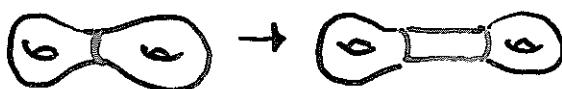
- \Rightarrow Wilson loop observables for gravity groups H_λ from Wilson loop observables of rotation group/Lorentz group
- \Rightarrow canonical pair of Wilson loop observables as real and Θ -component of R_λ -valued observable

Theorem

(Lorentzian $\lambda > 0, \lambda = 0, \lambda < 0$, Euclidean $\lambda < 0$)

The two canonical Wilson loop observables associated to closed, simple geodesic generate via the Poisson bracket the two fundamental geometry changing transformations: grafting and earthquake

grafting



earthquake



- real component \cong grafting \rightarrow "momentum of geodesic"
- Θ - component \cong earthquake \rightarrow "angular momentum of geodesic"
- grafting = earthquake with formal parameter Θ

(4)

The unified description of the phase space via Poisson-Lie structures

Lorentzian
 $\lambda > 0, \lambda = 0, \lambda < 0$
 Euclidean $\lambda < 0$

Poisson-structure given by classical r-matrix and associated Poisson-structures from theory of Poisson-Lie groups:
 particle \sim dual Poisson-Lie structure
 handle \sim Heisenberg double

\rightarrow unified description of phase space from unified description of Poisson-Lie groups

Classical r-matrices: $r = S_a \otimes J^a$ $S_a = P_a + \epsilon_{abc} n^b J^c$ $n^2 = -1$
 (classical doubles) $[J_a, J_b] = \epsilon_{abc} J^c$ $[J_a, S_b] = \epsilon_{abc} S^c - (n^b J_a - P_a)$

"natural" coordinates:

classical double \rightarrow factorisation of H_λ

$$H_\lambda \ni g = P(g) \cdot Q(g) \quad P \in H_1, Q \in \mathbb{R} \times \mathbb{R}^2$$

factorisation + identification $H_\lambda = H_1(R_\lambda) \Rightarrow$ coordinates

$$P = \sqrt{1 - \frac{P^2}{4}} + P^a J_a \quad Q = \sqrt{1 + \frac{q^2}{4}} + q^a S_a$$

dual Poisson-Lie structure and Heisenberg double

dual Poisson-Lie structure

$$\{q^a, q^b\} = \sqrt{1 + \frac{(q^a)^2}{4}} \epsilon^{abc} q_c$$

$$\{P^a, P^b\} = \sqrt{1 - \frac{P^2}{4}} (n^a P^b - n^b P^a)$$

$$\{q^a, P^b\} = \sqrt{1 + \frac{(q^a)^2}{4}} \epsilon^{abc} P_c - \sqrt{1 - \frac{P^2}{4}} (n^b q^a - \epsilon^{ab} (qn))$$

- "natural" coordinates common to H_λ ($\lambda, \lambda \geq 0, \lambda \neq 0$) in terms of which Poisson structure of particularly simple form
- unified description of phase space in which λ is a parameter (via $n, n^2 = \lambda$)

5.

Outlook and Conclusions

- unified descriptions of Lie groups in 3d gravity as unit (pseudo) quaternions over commutative ring

$$\left. \begin{array}{l} \mathrm{SL}(2, \mathbb{C}) \\ \mathrm{SU}(2) \times \mathbb{R}^3 \\ \mathrm{SU}(2) \times \mathrm{SU}(2) \end{array} \right\} = \mathrm{H}_1^E(R_1)$$

$$\left. \begin{array}{l} \mathrm{SL}(2, \mathbb{C}) \\ \mathrm{SL}(2, \mathbb{R}) \times \mathbb{R}^3 \\ \mathrm{SL}(2, \mathbb{R}) \times \mathrm{SL}(2, \mathbb{R}) \end{array} \right\} = \mathrm{H}_1^L(R_1)$$

- unified description of Lie bialgebra and Poisson-Lie structures in 3d gravity (Lorentzian $\lambda > 0, \lambda = 0, \lambda < 0$, Euclidean $\lambda = 0$)
 - classical r-matrices
 - factorisation
 - dual Poisson-Lie structure and Heisenberg double

\Rightarrow Physical applications:

- unified description of phase space and Poisson structure
- "natural" coordinates
- Canonical Wilson loop observables with clear physical interpretation (Hamiltonians for geometry change via earthquakes and grafting)

Open questions

- applications to quantisation ?
- unified description of quantum groups in 3d gravity ?
- "cosmological deformation" of quantum groups ?
- limit $\lambda \nearrow 0$ $\lambda \searrow 0$?
- representation theory ?